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A bilinear form associated to contact sub-conformal manifolds

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Abstract

We define a bilinear form associated to a sub-Riemannian contact manifold. It transforms by scalar multiples under sub-conformal transformations and with further hypothesis it is naturally defined on certain torus bundles over the contact manifold.
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1. Introduction

A pseudohermitian structure on a contact manifold M gives rise to a Lorentz conformal metric on a circle bundle over M (see [4] for a survey). That conformal structure is the same for all pseudohermitian structures defining the same CR structure. This was the method given in [10] generalizing the construction of the Lorentz form associated to a real strictly pseudoconvex hypersurfaces in \mathbb{C}^n in [8].

Another construction of the Lorentz structure for abstract CR manifolds is given in [1]. In fact, that was the first construction for an abstract CR manifold but its construction involves the construction of a Cartan connection [2,3,9,11] on a fiber bundle canonically associated to a CR manifold.

A natural generalization of pseudohermitian geometry on a contact manifold is sub-Riemannian geometry which is a metric structure only defined on the contact distribution. The sub-conformal structure associated to the sub-Riemannian manifold has an associated fiber bundle but in general it is not a principal bundle so that the approach in [1] becomes impossible.

The goal of this paper is to construct a form which changes by a scalar factor under sub-conformal transformations following the construction in [10] (see also [7] for a related construction). This construction is very general and holds even when there exists no natural circle bundle associated to the manifold. Instead, under appropriate hypothesis, there exists a torus bundle where the bilinear form is naturally defined (see [Theorem 3.1](#)) and eventually, under more

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restrictive conditions, is well defined on a circle bundle over the sub-Riemannian manifold (see [Theorem 3.2](#)). This generalizes the Fefferman's metric.

2. Sub-Riemannian and sub-conformal manifolds

In this section we define the geometrical structures we will use, namely the sub-Riemannian structures and sub-conformal structures. Let D be a contact distribution on a manifold M .

Definition 2.1.

1. (M, D, g) is a sub-Riemannian structure if g is a metric on D .
2. (M, D, \tilde{g}) is a sub-conformal structure if \tilde{g} is a conformal class of sub-Riemannian metrics.

Let $\pi : TM \rightarrow TM/D$ be the quotient map.

Definition 2.2. The Levi form $\alpha : D \times D \rightarrow TM/D$ is the skew-symmetric form defined as $\alpha(X, Y) = -\pi([X, Y])$.

Fixing a base v of TM/D defines the Levi form α_v as a real valued form. Let θ_v be the contact form of this distribution such that $\theta_v(\pi^{-1}v) = 1$, then the Levi form is given by

$$d\theta_v(X, Y) = \alpha_v(X, Y).$$

If we have a metric on D , define a skew-symmetric operator H_v on the distribution by

$$\alpha_v(X, Y) = g(H_v X, Y).$$

As α_v is non-degenerate, we can always choose v such that $\det H_v = 1$ and this determines a unique v ignoring orientation effects. Observe that if we let tg be a new metric and choose v as above, then

$$\alpha_{\frac{1}{t}v}(X, Y) = tg(H_v X, Y)$$

so the definition of H_v does not depend on a metric inside a conformal class of metrics. Fixing a metric on D , denote by H this operator. Its normal form is given in the following lemma.

Lemma 2.1. *Let V be a $2n$ dimensional real vector space with a scalar product. If H is a nondegenerated skew-symmetric operator, then there exists an orthonormal basis of V such that the matrix of H is*

$$A = \begin{pmatrix} & & & \begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \lambda_n \end{pmatrix} \\ & 0 & & \\ \begin{pmatrix} -\lambda_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & -\lambda_n \end{pmatrix} & & & 0 \end{pmatrix}$$

with $\lambda_i > 0$, $i = 1, \dots, n$.

We also need the following simple lemma which characterizes the subgroup of $SO(2n)$ commuting with A .

Lemma 2.2. *Suppose that A is such that $\lambda_{d_1+\dots+d_{k-1}+1} = \dots = \lambda_{d_1+\dots+d_k} = v_k$ for $1 \leq k \leq r$, with $d_1 + \dots + d_r = n$, and $v_1 < v_2 < \dots < v_r$, where the v_k are real numbers, and that $A \in SO(2n)$ satisfies $A\Lambda A^T = \Lambda$. Then $A \in U(d_1) \times \dots \times U(d_r)$.*

3. Sub-Riemannian geometry

Let (M, D, g) be a sub-Riemannian manifold of dimension $2n + 1$, where D is a contact distribution on M , and g a positive quadratic form on D . We will further suppose that TM/D is oriented.

We consider the $SO(2n)$ bundle E of coframes (θ, θ^i) on M such that the θ^i restricted to D are orthonormal, θ is the positive contact form defined such that

$$d\theta = h_{ij}\theta^i \wedge \theta^j, \quad (1)$$

with $h_{ij} = -h_{ji}$ and $\det h_{ij} = 1$. Observe that a change in coframes given by $\bar{\theta}^i = a_j^i \theta^j$, $(a_j^i) \in SO(2n)$ implies that $\bar{h}_{ij} = a_k^i h_{kl} a_l^j$. On E we consider the tautological forms defined by θ, θ^i which we denote by the same letters. E is a principal fiber bundle with a right action by $SO(2n)$. We will consider the coframes as line vectors where $SO(2n)$ acts by matrix multiplication from the right.

Proposition 3.1. (See [6,12]) *There exist unique connection forms ω_j^i and torsion forms τ^i on E satisfying*

$$d\theta^i = \theta^j \wedge \omega_j^i + \theta \wedge \tau^i, \quad (2)$$

with $\omega_j^i = -\omega_i^j$ and

$$\sum \tau^i \wedge \theta^i = 0. \quad (3)$$

Proof. Let $\tilde{\omega}_j^i$ and $\tilde{\tau}^i$ be any forms satisfying the first equation. If ω_j^i and τ^i also satisfy the equation, then

$$\theta^j \wedge (\omega_j^i - \tilde{\omega}_j^i) + \theta \wedge (\tau^i - \tilde{\tau}^i) = 0.$$

From Cartan's lemma we have

$$\begin{aligned} \omega_j^i - \tilde{\omega}_j^i &= a_{jk}^i \theta^k + b_j^i \theta, \\ \tau^i - \tilde{\tau}^i &= b_k^i \theta^k \end{aligned}$$

with $a_{jk}^i = a_{kj}^i$. We will choose a_{jk}^i, b_j^i such that the conditions in the theorem be satisfied for ω_j^i, τ^i . To verify condition (3) we must have

$$0 = \sum \tau^i \wedge \theta^i = \sum \tilde{\tau}^i \wedge \theta^i + \sum \sum b_k^i \theta^k \wedge \theta^i.$$

If we write $\tilde{\tau}^i = \tilde{\tau}_k^i \theta^k$, then

$$\sum \sum (\tilde{\tau}_k^i + b_k^i) \theta^k \wedge \theta^i = 0$$

and using Cartan's lemma again $\tilde{\tau}_k^i + b_k^i = a_k^i$ with $a_k^i = a_i^k$. On the other hand if $\omega_j^i = -\omega_i^j$ is satisfied, and writing $\tilde{\omega}_j^i = \tilde{\omega}_{jk}^i \theta^k + \tilde{w}_j^i \theta$ we obtain

$$(\tilde{\omega}_{jk}^i + \tilde{\omega}_{ik}^j + a_{jk}^i + a_{ik}^j) \theta^k + (\tilde{w}_j^i + \tilde{w}_i^j + b_j^i + b_i^j) \theta = 0.$$

We get two equations

$$\begin{aligned} \tilde{w}_j^i + \tilde{w}_i^j + a_j^i + a_i^j - \tilde{\tau}_j^i - \tilde{\tau}_i^j &= 0, \\ \tilde{\omega}_{jk}^i + \tilde{\omega}_{ik}^j + a_{jk}^i + a_{ik}^j &= 0. \end{aligned}$$

The first equation, recalling that a_j^i is symmetric, has solution $a_j^i = \frac{\tilde{\tau}_j^i + \tilde{\tau}_i^j}{2} - \frac{\tilde{w}_j^i + \tilde{w}_i^j}{2}$ therefore b_j^i is determined. The second equation can be solved using the permutation trick, as in Riemannian geometry. \square

Eq. (3) is equivalent to $\tau^i = \tau_j^i \theta^j$, with $\tau_j^i = \tau_i^j$. If we differentiate (1), and apply (2) we get

$$(dh_{ij} - h_{kj} \omega_i^k + h_{ki} \omega_j^k) \theta^i \wedge \theta^j + 2h_{ij} \tau^i \wedge \theta^j \wedge \theta = 0.$$

A simple computation shows that there exist unique functions b_{ijk} and b_{ij} so that we can write

$$dh_{ij} - h_{kj}\omega_i^k + h_{ki}\omega_j^k = b_{ijk}\theta^k + b_{ij}\theta \quad (4)$$

and

$$2h_{ij}\tau^i \wedge \theta^j = -b_{ij}\theta^i \wedge \theta^j, \quad (5)$$

where $b_{ijk} = -b_{jik}$, $b_{ijk} + b_{jki} + b_{kij} = 0$, $b_{ij} = -b_{ji}$.

We will use the following notations:

$$\Omega = (\omega_j^i),$$

$$H = (h_{ij}) \quad \text{and} \quad H^{-1} = (h^{ij}).$$

Definition 3.1. On E we define,

$$\varsigma = \text{Tr}(H^{-1}\Omega) = h^{ji}\omega_i^j.$$

3.1. Conformal change in the sub-Riemannian metric

In this section we will study the transformation in the connection forms when the metric on D undergoes a conformal change of the form

$$g' = e^{2f}g$$

where f is a real function on M . For this we need to compare the structure equations for the metrics g and g' . Let's first introduce some notation (a study of the invariants of sub-conformal structures can be found in [5]).

Define f_0 and f_i using the formula

$$df = f_0\theta + f_i\theta^i, \quad (6)$$

and write

$$f^i = h^{ij}f_j.$$

If we differentiate (6), we get

$$(df_0 - f_i\tau^i) \wedge \theta + (df_j - f_i\omega_j^i + f_0h_{ij}\theta^i) \wedge \theta^j = 0.$$

Applying Cartan's lemma we obtain

$$df_j - f_i\omega_j^i + f_0h_{ij}\theta^i = f_{jk}\theta^k + f_{j0}\theta,$$

$$df_0 - f_i\tau^i = f_{0j}\theta^j + f_{00}\theta,$$

with $f_{jk} = f_{kj}$ and $f_{0j} = f_{j0}$. It is a direct verification, applying (4), that

$$dh^{ij} = h^{jk}\omega_k^i - h^{ik}\omega_k^j + h^{ik}(b_{klm}\theta^m + b_{kl}\theta)h^{jl}.$$

Then

$$df^i + f^j\omega_j^i - f_0\theta^i = f_j^i\theta^j + f_0^i\theta, \quad (7)$$

where

$$f_j^i = h^{ik}(f_{kj} - b_{klj}f^l)$$

and $f_0^i = h^{ik}(f_{k0} - b_{kl}f^l)$.

The contact form associated to g' is

$$\theta' = e^{2f}\theta.$$

Verifying that

$$d\theta' = h_{ij}\theta'^i \wedge \theta'^j, \quad (8)$$

we obtain that the new coframes are given by

$$\theta'^i = e^f(\theta^i + f^i\theta) \quad (9)$$

with $h'_{ij} = h_{ij}$. Let E' be the bundle of coframes (θ', θ'^i) associated to the sub-Riemannian manifold (M, D, g') .

Proposition 3.2. *The application*

$$F : E \rightarrow E'$$

given by

$$F(\theta, \theta^i) = (\theta', \theta'^i) = (e^{2f}\theta, e^f(\theta^i + f^i\theta))$$

is a isomorphism of $SO(2n)$ -bundles.

Proof. Let $(\theta, \bar{\theta}^i)$ be a new coframe of E , with $\bar{\theta}^i = a_j^i\theta^j$, $(a_j^i) \in SO(2n)$. From $d\theta = \bar{h}_{ij}\bar{\theta}^i \wedge \bar{\theta}^j$ we obtain $\bar{h}^{ij} = a_k^i h^{kl} a_l^j$. Then $F(\theta, \bar{\theta}^i) = (\theta', \bar{\theta}'^i)$, where $\bar{\theta}'^i = e^f(\bar{\theta}^i + \bar{f}^i\theta)$, $df = \bar{f}_j\bar{\theta}^j + \bar{f}_0\theta$, and $\bar{f}^i = \bar{h}^{ij}\bar{f}_j$. That implies $\bar{f}_i = a_j^i f_j$, $\bar{f}^i = a_k^i f^k$ and $\bar{\theta}'^i = e^f(a_j^i\theta^j + a_j^i f^j\theta) = a_j^i\theta'^j$. We proved that

$$F(\theta, a_j^i\theta^j) = (\theta', a_j^i\theta'^j),$$

what ends the proof. \square

We consider from now on the tautological forms on E' using, by abuse of notation, the same letters θ'^j and θ' . As before there exist unique forms $\omega_j'^i$ and τ'^i such that

$$d\theta'^i = \theta'^j \wedge \omega_j'^i + \theta' \wedge \tau'^i, \quad (10)$$

$$\omega_j'^i = -\omega_i'^j, \text{ and } \sum \tau'^i \wedge \theta'^i = 0.$$

In what follows, we will omit the function F when comparing the bundles E and E' . That is, we will write, by abuse of notation, $\alpha' = F^*(\alpha')$ for a form α' defined on E' .

Differentiating (9) and applying (2) and (10), we obtain

Proposition 3.3. *The connection and torsion forms of E and E' satisfy the following formulae:*

$$\omega_j'^i = \omega_j^i + e^{-f}(f_j\delta_k^i - f_i\delta_k^j + f^i h_{jk} - f^j h_{ik} - f^k h_{ij})\theta'^k + e^{-2f}\left(f^j f_i - f^i f_j + \frac{1}{2}f_j^i - \frac{1}{2}f_i^j\right)\theta' \quad (11)$$

and

$$\tau'^i = e^{-2f}\left(\tau_j^i + f_0\delta_j^i + f^i f_j + f^j f_i - \frac{1}{2}f_i^j - \frac{1}{2}f_j^i\right)\theta'^j.$$

It follows from (11) the following

Proposition 3.4. $\varsigma = \text{Tr}(H^{-1}\Omega)$ and $\varsigma' = \text{Tr}(H^{-1}\Omega')$ are related by

$$\varsigma' = \varsigma + (2n+4)f^i\theta^i + ((2n+2)f^i f^i + h^{ij}f_j^i)\theta.$$

Applying (7) we get

$$d(f^i\theta^i) = f_j^i\theta^j \wedge \theta^i + \theta \wedge (f_0^i\theta^i + f^i\tau^i).$$

Then

$$d\zeta' = d\zeta + ((2n+4)f_i^j + ((2n+2)f^k f^k + h^{kl} f_l^k)h_{ij})\theta^i \wedge \theta^j \mod \theta. \quad (12)$$

Our goal is to construct a conformally invariant bilinear form on a certain bundle over M using ζ , $d\zeta$ and the tautological forms θ^i and θ . In order to do so we first need to reduce the structure group of E . Eventually we will impose that H is constant on the reduced bundle, but we will carry our computation in a more general setting with some regularity assumptions on H .

3.2. Reduction of the structure group

We suppose now that the canonical form Λ of $H = (h_{ij})$ as in Lemma 2.2 has in every point of M r values ν_k , each one with multiplicity d_k . More explicitly, the ν_k are real functions on M .

Definition 3.2. E_1 is the subset of points of E such that $H = \Lambda$.

From Lemma 2.2 we have that E_1 is a $U(d_1) \times \cdots \times U(d_r)$ subbundle of E . We denote a coframe in E_1 by θ^{ik} where $1 \leq k \leq r$ and $d_1 + \cdots + d_{k-1} + 1 \leq i_k \leq d_1 + \cdots + d_k$ with $d_1 + \cdots + d_r = n$.

If $Y = Y_1 + \cdots + Y_r$ with $Y_k \in su(d_k)$, then $\Lambda^{-1}Y = 2\nu_1^{-1}J_1Y_1 + \cdots + 2\nu_r^{-1}J_rY_r$, where J_k is a linear operator such that $J_k^*\theta^{i_l} = -\delta_k^l\theta^{i_l+n}$ and $J_k^*\theta^{i_l+n} = \delta_k^l\theta^{i_l}$. Observe that $J_k^*\theta^i \neq 0$ only for $d_1 + \cdots + d_{k-1} + 1 \leq i \leq d_1 + \cdots + d_k$.

3.3. The torus bundle over M

The subgroup $SU(d_1) \times \cdots \times SU(d_r)$ is normal in $U(d_1) \times \cdots \times U(d_r)$. We define \mathbf{T} as the quotient bundle of E_1 by $SU(d_1) \times \cdots \times SU(d_r)$. \mathbf{T} is a $U(1) \times \cdots \times U(1)$ bundle, i.e. \mathbf{T} is a r -torus principal bundle over M :

Proposition 3.5. $\mathbf{T} = E_1/SU(d_1) \times \cdots \times SU(d_r)$ is a $U(1) \times \cdots \times U(1)$ -principal bundle.

Parts of the sub-Riemannian connection descend to forms defined on the torus bundle. We use the following criterion:

A differential form φ on E projects on \mathbf{T} if and only if

1. $R_g^*\varphi = \varphi$ for every $g \in SU(d_1) \times \cdots \times SU(d_r)$,
2. $\varphi(X^*) = 0$ for every $X \in su(d_1) + \cdots + su(d_r)$.

Restricted to E_1 we have

$$\zeta = \text{Tr}(\Lambda^{-1}\Omega) = \sum_k \sum_{i_k} \frac{2}{\nu_k} \omega_{i_k+n}^{i_k},$$

where $d_{k-1} + 1 \leq i_k \leq d_k$ and $1 \leq k \leq r$.

Also,

Definition 3.3. On E_1 we define,

$$\omega_k = 2 \sum_{i_k} \omega_{i_k+n}^{i_k}$$

where $d_{k-1} + 1 \leq i_k \leq d_k$.

Proposition 3.6. The forms ζ and ω_k project to $\mathbf{T} = E_1/SU(d_1) \times \cdots \times SU(d_r)$.

Proof. We prove first the result for the form ζ . In order to verify $R_a^*\zeta = \zeta$ for $a \in U(d_1) \times \cdots \times U(d_r)$, it suffice to verify the formula on vertical vectors, because ζ vanishes on horizontal vectors. Suppose $X \in u(d_1) + \cdots + u(d_r)$,

$a \in U(d_1) \times \cdots \times U(d_r)$ and let X^* be the vertical vector field on E_1 induced by X . From $R_{a*}X^* = (a^{-1}Xa)^*$ and observing that $a\Lambda = \Lambda a$, we have

$$R_a^*\zeta(X^*) = \zeta(R_{a*}X^*) = \text{Tr}(\Lambda^{-1}a^{-1}Xa) = \text{Tr}(\Lambda^{-1}X) = \zeta(X^*).$$

To end the proof it is enough to verify that if $Y \in su(d_1) + \cdots + su(d_r)$

$$\text{Tr } \Lambda^{-1}Y = 0.$$

Recall that if $Y = Y_1 + \cdots + Y_r$ with $Y_k \in su(d_k)$, then $\Lambda^{-1}Y = 2v_1^{-1}J_1Y_1 + \cdots + 2v_r^{-1}J_rY_r$ and $\text{Tr } \Lambda^{-1}Y = 2v_k^{-1}\text{Tr}(J_kY_k) = 0$.

The same argument shows that the forms $\omega_k = 2\sum_{i_k} \omega_{i_k+n}^{i_k}$ project to \mathbf{T} . \square

Proposition 3.7. *The projected forms $(\omega_1, \dots, \omega_r)$ define a connection on \mathbf{T} with values in $u(1) + \cdots + u(1)$.*

Proposition 3.8. *The form $d\zeta$ descends to a form on M if and only if H is constant.*

Proof. As $R_a^*\zeta = \zeta$ for every $a \in U(d_1) \times \cdots \times U(d_r)$, then $L_{X^*}\zeta = 0$ for every $X \in u(d_1) + \cdots + u(d_r)$. We write $d(i(X^*)\zeta) = d(\sum_k \frac{1}{v_k} \omega_k(X^*))$ and observe that $\omega_k(X^*)$ is constant for every X^* . Therefore $d(i(X^*)\zeta) = 0$ if and only if v_k are constant.

It follows from the formula $L_{X^*} = di(X^*) + i(X^*)d$ that $i(X^*)d\zeta = 0$. We conclude that $d\zeta$ is projectable on M . The same argument shows that the forms $d\omega_k$ can always be projected. \square

In the rest of that section we suppose that H is constant. Given a two form

$$\varpi = V_{ij}\theta^i \wedge \theta^j + V_i\theta^i \wedge \theta$$

on M , define

$$\text{Tr } \varpi = h^{ij} V_{ji}.$$

We can now define on \mathbf{T} the form

Definition 3.4.

$$\sigma = \frac{1}{n+2} \left(\zeta - \frac{1}{4(n+1)} \text{Tr}(d\zeta)\theta \right).$$

We define now a bilinear form on \mathbf{T} of type $(2n+1, 1, r-1)$, that is, with $2n+1$ positive eigenvalues, 1 negative eigenvalue and with a $(r-1)$ -dimensional kernel.

Definition 3.5. Let b be the bilinear symmetric form of type $(2n+1, 1, r-1)$

$$b = \theta^i \theta^i + \theta \sigma.$$

Observe that for any 2-form ϖ on M , $\text{Tr}'(\varpi) = \text{Tr}(\varpi)e^{2f}$. From (12) we obtain

Lemma 3.1.

$$\text{Tr}' d\zeta' = (\text{Tr } d\zeta + (4n+4)(f_j^i h^{ij} + n f^i f^i))e^{-2f}$$

so

Proposition 3.9.

$$\sigma' = \sigma - 2f^i \theta^i - f^i f^i \theta.$$

Putting together the formulas above we finally obtain the conformal invariance of the bilinear form.

Theorem 3.1. *Let (M, D, g) be a sub-Riemannian manifold such that H is constant on E_1 . Then there exists a torus bundle \mathbf{T} over M and the bilinear form*

$$b = \theta^i \theta^i + \theta \sigma$$

on \mathbf{T} is a conformal invariant, i.e.,

$$b' = e^{2f} b,$$

if $g' = e^{2f} g$ on D .

Proof. From the definition we get

$$b' = e^{2f} (\theta^i + f^i \theta) (\theta^i + f^i \theta) + e^{2f} \theta (\sigma - 2f^i \theta^i - f^i f^i \theta) = e^{2f} b. \quad \square$$

Corollary 3.1. *When $H^2 = -\text{Id}$ on E_1 the torus bundle \mathbf{T} is a $U(1)$ bundle and the bilinear form b is a conformally invariant Lorentz metric*

3.4. Circle bundles

In that section we suppose that H is constant on \mathbf{T} .

Consider now

$$g = \{X \in u(1) + \cdots + u(1): \sigma(X^*) = 0\}.$$

As $\sigma(X^*) = \frac{1}{n+2} \sum_k \frac{\omega_k(X^*)}{v_k} = 0$, $G = \exp g$ is a closed subgroup of $U(1) \times \cdots \times U(1)$ if and only if there exists relatively prime positive integers m_1, \dots, m_r such that

$$m_1 v_1 = m_2 v_2 = \cdots = m_r v_r.$$

We may now define the $U(1)$ bundle $\mathbf{N} = \mathbf{T}/G$. We have proved

Theorem 3.2. *The bilinear form b descends to a Lorentz metric on \mathbf{N} defined by*

$$L = \theta^i \theta^i + \theta \sigma$$

which is conformally invariant, that is, if $g' = e^{2f} g$ on D then $L' = e^{2f} L$ on \mathbf{N} .

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